Keyframe Programming

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Creating a New Project

On the Getting Started window, select **New project...**, If the window does not appear, select **New project...** from the **File** menu
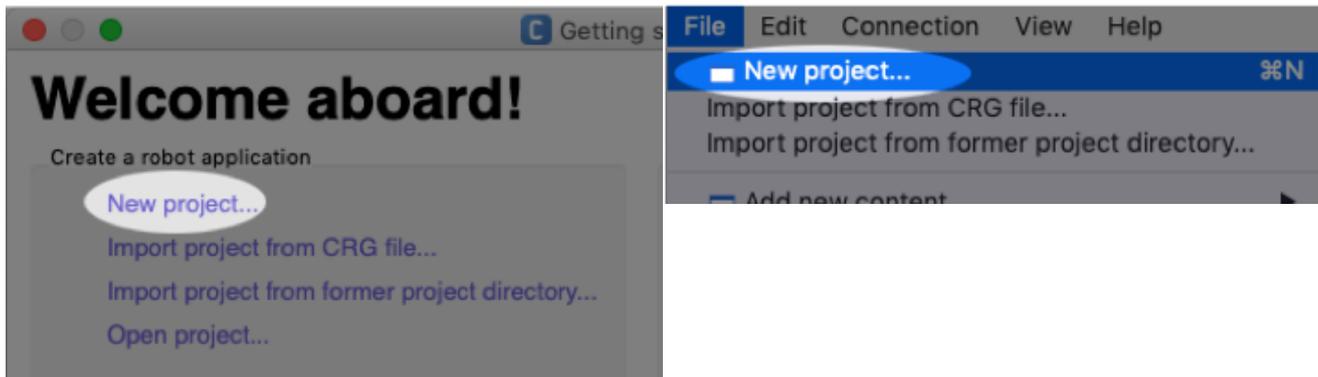
Connecting to the NAO

With both your NAO and computer connected to the same wireless network, click the **Connect to** button in the **toolbar** or select **Connect to...** from the **Connection** menu

A list of virtual/simulated and physical robots will be displayed. If your NAO appears in the list and is green, highlight it and press the **select** button.

A real robot - **not ready to connect to.**

A real robot - **ready to connect to.**

A virtual robot - **you can connect to this robot.**

If the robot stays in this state, try restarting the NAO and Choregraphe

Some commands in Choregraphe will not be available